

LIMITATIONS IN LINEAR PROGRAMMING PROBLEMS

Rekha.R.R

*Research Scholar
 Department of Mathematics
 Bharath Institute of Higher Education and
 Research
 Tamilnadu*

Dr. N.Ramya

*Assistant Professor
 Department of Mathematics
 Bharath Institute of Higher Education and
 Research
 Tamilnadu*

Abstract—In this paper a new methodology is proposed to identify the jobless restrictions in linear programming problems and linked with the prevailing three techniques and analyzing the computational efforts by solving various size of linear programming problems.

Keywords—Linear programming,

I. INTRODUCTION

In solving an LPP, we tend to contain all conceivable restrictions that will increase the number of recapitulations and computational effort. It is well known that for most of the large scale LP problems, slightly small part of restrictions are intricate in the realistic region. The aim of this work is to compare the new approach with the earlier method by using some of the restrictions.

II. PROPOSED TECHNIQUE

In this section, a new tactic is advised to select the most preventive constraint. The steps of the proposed method are as follows. [5-10]

Step 1:

Divide the left hand side value by each of the reserve restrictions along the relevant

co- ordinate axis.

Step 2:

Compute $S_i = \sum_{j=1}^n [\bar{a}_{ij}]$

Step 3:

Select a highest limiting restriction equivalent to l . Where $l = \arg \text{minimum}_i(S_i)$,

Step 4:

If $A_l X \leq b_k$, is the unnecessary if $\alpha_k^l < b_k$ Where α_k^l is the optimal value of LP_k^l , where LP_k^l is

$$LP_k^l: \text{Maximize } \alpha_k^l = A_l X$$

$$\text{Subject to } A_l X \leq b_l$$

$$0 \leq X \leq U$$

III. NUMERICAL ILLUSTRATION

Example:

$$\text{Maximize } z = x_1 + x_2$$

Sub to

$$x_1 + x_2 \leq 3 \text{ ----- } 1$$

$$x_1 + 2x_2 \leq 5 \text{ ----- } 2$$

$$3x_1 + x_2 \leq 6 \text{ ----- } 3$$

Solution:

$$\text{Here } C = (1 \ 1)$$

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 3 & 1 \end{pmatrix}$$

$$b^T = (3 \ 5 \ 6)$$

$$U^T = (25 \ 20)$$

$$S_1 = 75$$

$$S_2 = 70$$

$$S_3 = 75$$

$$\text{Maximize } \alpha_k^l = A_l X$$

$$\text{Subject to } A_l X \leq b_l, \text{ where } l = \arg \min_i \{S_i\},$$

$$l = 2$$

$$0 \leq X \leq U$$

$$(i) \ \alpha_1^2 = (1 \ 1)$$

$$(1 \ 2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq 100$$

$\alpha_1^2 = 300$, constraint 1 is not the unnecessary constraint. [11-15]

$$(ii) \ \alpha_3^2 = (3 \ 1)$$

$$(1 \ 2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq 100$$

$\alpha_3^2 = 300$, constraint 3 is the unnecessary constraint. [16-23]

Therefore constraint 3 is the unnecessary constraint.

IV. CONCLUSION

In this paper, earlier technique has been compared with mentioned procedure. This new procedure is less time consuming as associated with the previous method. This new approach requires small number of computational steps. Both methods were identified same dismissed limitations. Therefore, it is easy to identify the unnecessary constraints even in a large scale linear programming problems. And also can compute the time in milliseconds and micro seconds. Earlier approach taken more work and more time.

Comparative results of the both methods:

S.No.	No. of Constraints	No. of variable	Earlier Method	Proposed Method
1	3	2	1(3)	1(3)
2	3	2	0	-

3	3	2	1(3)	1(3)
4	4	3	2(3,4)	2(3,4)
5	4	3	2(1,4)	2(1,4)
6	3	3	1(3)	1(3)
7	4	5	2(3,4)	2(3,4)
8	5	2	4(2,3,4,5)	4(2,3,4,5)
9	5	4	2(2,4)	2(2,4)

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